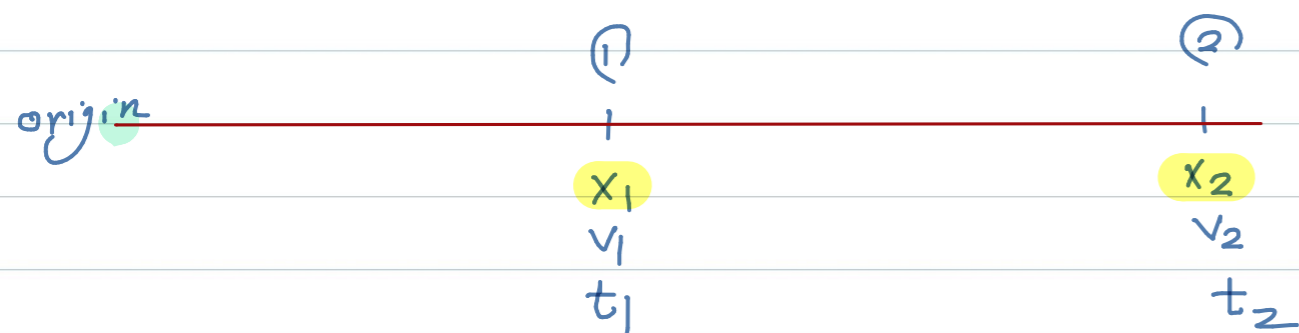


Kinematics of Particles Chapter 1

Rectilinear Motion :-

- Position
- velocity
- acceleration



Position :-

x_1 } Right of origin (+)
 x_2 } Left of origin (-)

Displacement :- (vector)

$$\Delta x = x_2 - x_1$$

$\xrightarrow{+}$
 $\xleftarrow{-}$

Distance travelled :- (scalar)



Average Velocity :- [Vector]

$$v_{av} = \frac{\Delta x}{\Delta t}$$

$\xrightarrow{+}$
 $\xleftarrow{-}$

Instantaneous velocity :- (vector)

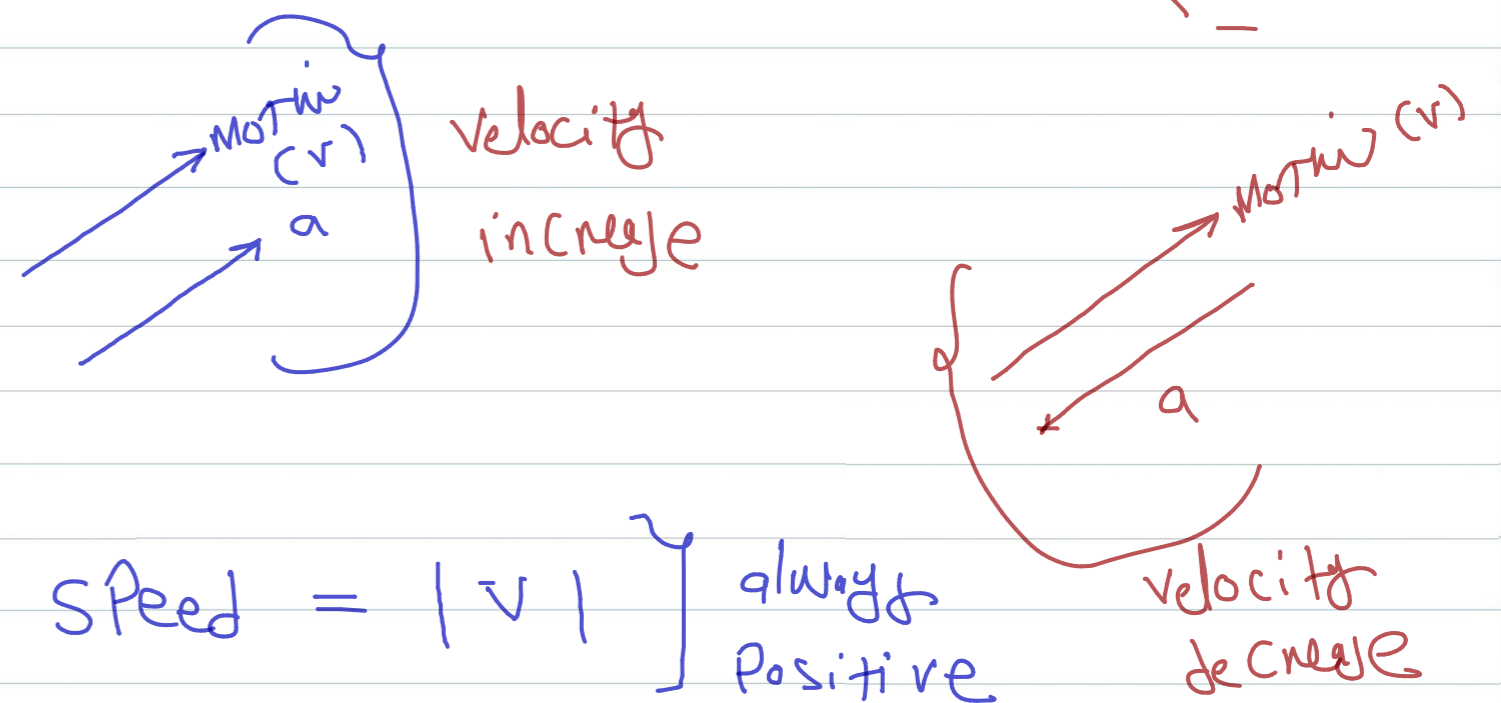
$$v = \frac{dx}{dt}$$

$\xrightarrow{+}$
 $\xleftarrow{-}$

Instantaneous acceleration :- (vector)

$$a = \frac{dv}{dt} = \frac{d^2x}{dt^2}$$

$\xrightarrow{+}$
 $\xleftarrow{-}$



Speed = |v| } always positive
 } velocity decrease

$v = \frac{dx}{dt}$ derivative x
 $a = \frac{dv}{dt}$ v
 a

$\int_{x_0}^x dx = \int_{v_0}^v v dt$
 $\int_{v_0}^v dv = \int_{t_0}^t a dt$

PROBLEM 11.1

A snowboarder starts from rest at the top of a double black diamond hill. As he rides down the slope, GPS coordinates are used to determine his displacement as a function of time: $x = 0.5t^3 + t^2 + 2t$ where x and t are expressed in ft and seconds, respectively. Determine the position, velocity, and acceleration of the boarder when $t = 5$ seconds.

$$x = 0.5t^3 + t^2 + 2t$$

$$v = \frac{dx}{dt} = 1.5t^2 + 2t + 2$$

$$a = \frac{dv}{dt} = 3t + 2$$

@ $t = 5$ Sec

$$x = 0.5(5)^3 + (5)^2 + 2(5) = 97.5 \text{ Ft}$$

$$v = 1.5(5)^2 + 2(5) + 2 = 49.5 \text{ Ft/s}$$

$$a = 3(5) + 2 = 17 \text{ Ft/s}^2$$

Example Problem 1.1

- The curvilinear motion of a particle is represented by the equation :

$$s = 20t + 4t^2 - 3t^3$$

- What is the particle's initial velocity?

(A) 20 m/s

(B) 25 m/s

(C) 30 m/s

(D) 32 m/s

@ t=0

$$v = \frac{ds}{dt} = 20 + 8t - 9t^2$$

$$\text{@ } t=0 \Rightarrow v = 20 + 8(0) - 9(0)^2$$

$$v = 20 \text{ m/s}$$

Example Problem 1.2

- The curvilinear motion of a particle is represented by the equation

$$s = 20t + 4t^2 - 3t^3$$

- What is the acceleration of the particle at time t=0?

(A) 2 m/s²

(B) 3 m/s²

(C) 5 m/s²

(D) 8 m/s²

$$a = \frac{dv}{dt} = 8 - 18t$$

$$\text{@ } t=0 \Rightarrow a = 8 \text{ m/s}^2$$

Example Problem 1.3

- The curvilinear motion of a particle is represented by the equation

$$s = 20t + 4t^2 - 3t^3$$

- What is the maximum speed reached by the particle?

(A) 21.8 m/s

(B) 27.9 m/s

(C) 34.6 m/s

(D) 48.0 m/s

$$s = 20t + 4t^2 - 3t^3$$

$$v = \frac{ds}{dt} = 20 + 8t - 9t^2$$

$$a = \frac{dv}{dt} = 8 - 18t$$

when $a = 0$

$$8 - 18t = 0$$

$$t = \frac{8}{18} = 0.444 \text{ sec}$$

v_{Max} @ $a = 0$

$$v_{\text{Max}} = 20 + 8(0.444) - 9(0.444)^2$$
$$= 21.8 \text{ m/s}$$

Example Problem 11.1

- The position of a particle which moves along a straight line is defined by the relation

$$x = t^3 - 6t^2 - 15t + 40,$$

where x is expressed in meters and t in seconds.

Determine

- the time at which the velocity will be zero,
- the position and distance traveled by the particle at that time,
- the acceleration of the particle at that time,
- the distance traveled by the particle from $t=4$ s to 6 s.

$$x = t^3 - 6t^2 - 15t + 40$$

$$v = \frac{dx}{dt} = 3t^2 - 12t - 15$$

$$a = \frac{dv}{dt} = 6t - 12$$

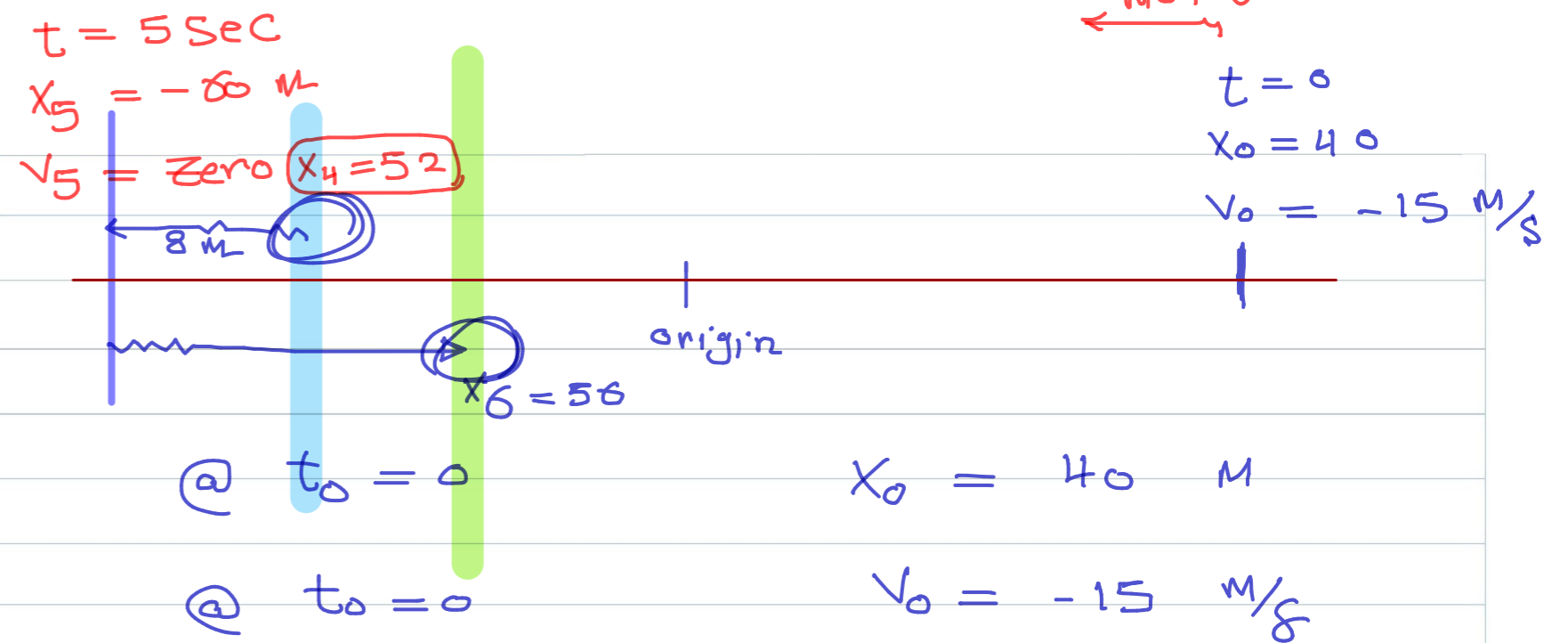
a) $t = ??$ @ $v = 0$ } Changing direction

$$3t^2 - 12t - 15 = 0$$

By Calculatⁿ
 $t = -1$ sec Rejected
 $t = 5$ sec

b) @ $t = 5$ sec $x_5 = ??$

$$x_5 = 5^3 - 6(5)^2 - 15(5) + 40 = -60 \text{ m}$$



$$\text{Distance travelled} = 40 + 60 = 100 \text{ m}$$

c) $a_5 = 6(5) - 12 = 18 \text{ m/s}^2$

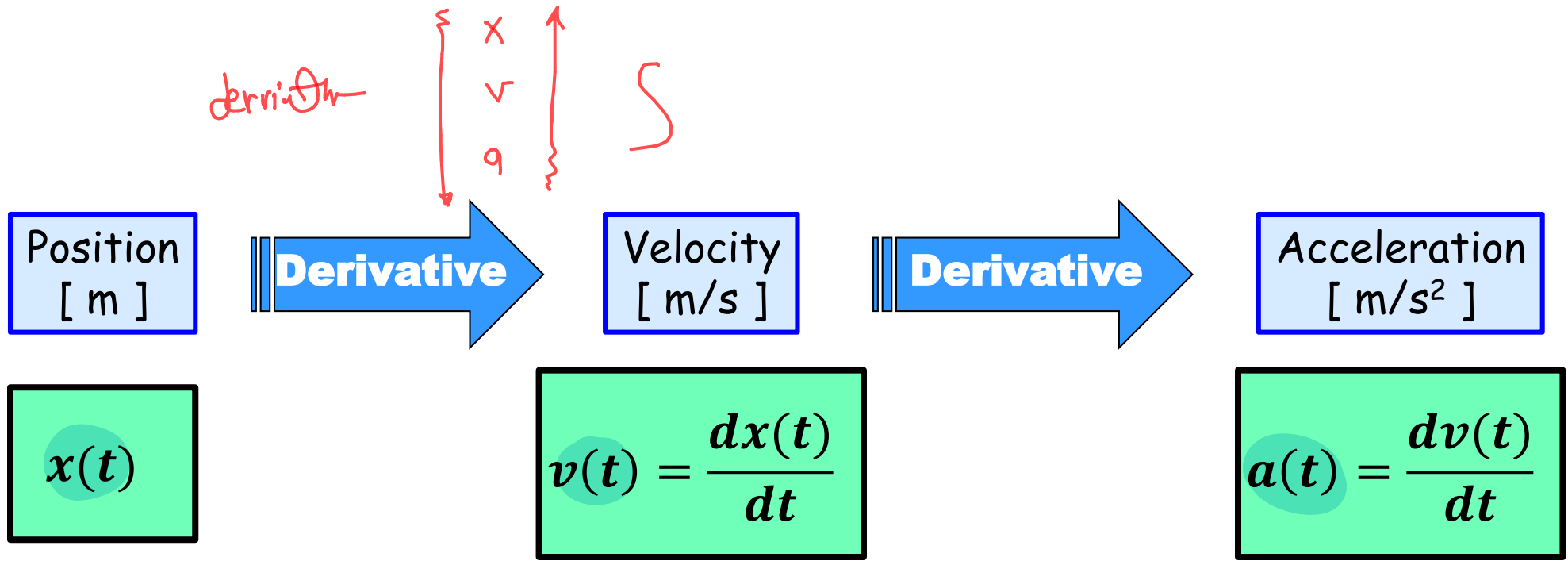
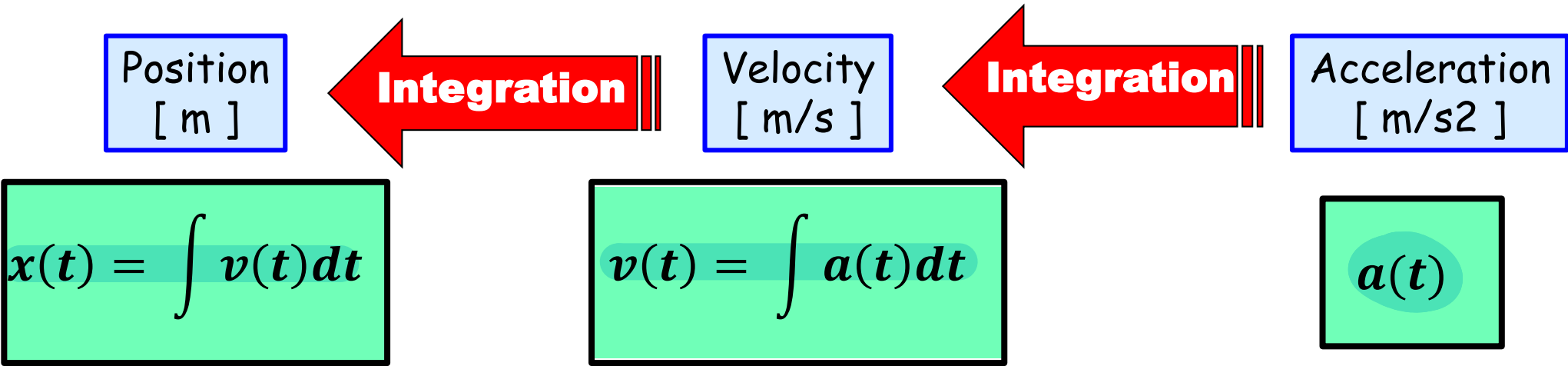
d) $x_4 = (4)^3 - 6(4)^2 - 15(4) + 40$ } @ $t = 4 \text{ sec}$
 $= -52 \text{ m}$

$x_6 = (6)^3 - 6(6)^2 - 15(6) + 40$ } @ $t = 6 \text{ sec}$
 $= -50 \text{ m}$

Distance travelled (From $t = 4 \text{ sec} \rightarrow t = 5 \text{ sec}$)
 $= 60 - 52 = 8 \text{ m}$

Distance travelled (From $t = 5 \text{ sec} \rightarrow t = 6 \text{ sec}$)
 $= 60 - 50 = 10 \text{ m}$

total distance travelled = $10 + 8 = 18 \text{ m}$



1. $a = f(t)$. The Acceleration Is a Given Function of t .

$$\int_{v_0}^v dv = \int_0^t f(t) dt$$
$$v - v_0 = \int_0^t f(t) dt$$

2. $a = f(x)$. The Acceleration Is a Given Function of x .

$$\int_{v_0}^v v dv = \int_{x_0}^x f(x) dx$$
$$\frac{1}{2}v^2 - \frac{1}{2}v_0^2 = \int_{x_0}^x f(x) dx$$

3. $a = f(v)$. The Acceleration Is a Given Function of v .

$$dt = \frac{dv}{f(v)} \quad dx = \frac{v dv}{f(v)}$$

Sample Problem 11.3 (integration)

- The brake mechanism used to reduce recoil in certain types of guns consists essentially of a piston attached to the barrel and moving in a fixed cylinder filled with oil.
- As the barrel recoils with an initial velocity v_0 , the piston moves and oil is forced through orifices in the piston, causing the piston and the barrel to decelerate at a rate proportional to their velocity, that is **$a = -kv$** .
- Express (a) v in terms of t , (b) x in terms of t , (c) v in terms of x .** Draw the corresponding motion curves

$$a = -kv$$

$$(a) \quad a = \frac{dv}{dt} = -kv$$

$$\frac{dv}{v} = -k dt$$

$$\int_{v_0}^v \frac{dv}{v} = -k \int_0^t dt$$

$$\ln v \Big|_{v_0}^v = -kt$$

$$\ln \frac{v}{v_0} = -kt$$

$$\frac{v}{v_0} = e^{-kt}$$

$$v = v_0 e^{-kt}$$

$$(b) \quad v = \frac{dx}{dt} = v_0 e^{-kt}$$

$$\int_0^x dx = \int_0^t v_0 e^{-kt} dt$$

$$x = -\frac{v_0}{k} \left(e^{-kt} \Big|_0^t \right)$$

$$x = -\frac{v_0}{k} (e^{-kt} - 1)$$

(c)

$$a = v \frac{dv}{dx} = -kv$$

$$\int_{v_0}^v dv = -k \int_0^x dx$$

$$v - v_0 = -kx$$

$$v = v_0 - kx$$

* Motion with Constant acceleration :-

$$a = \frac{dv}{dt}$$

$$v = v_0 + at \quad (\text{No } - x)$$

$$x = x_0 + v_0 t + \frac{1}{2} at^2 \quad (\text{No } - v)$$

$$v^2 = v_0^2 + 2a(x - x_0) \quad (\text{No } - t)$$

v_0

v

x

t

a

Free Fall bodies :-

→ vertically UP

→ vertically down

$$a_y = -g = 9.8 \frac{m}{s^2} \rightarrow \text{dropped}$$

$$v = v_0 + a_y t$$

$$y = y_0 + v_0 t + \frac{1}{2} a_y t^2$$

$$v^2 = v_0^2 + 2a_y (y - y_0)$$

